



Presentation Beijing

COMPANY INFORMATION

IMAGE SYSTEMS GROUP

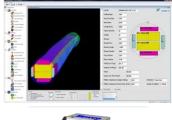
DigitalVision





Optimisation of image quality and output in broadcast and movie industry



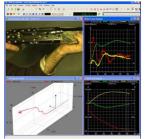




Optimisation by image analysis of sawmill industry







Creation of scientific data output from images Turnover: 25 MEUR

Employees: 96

Offices:

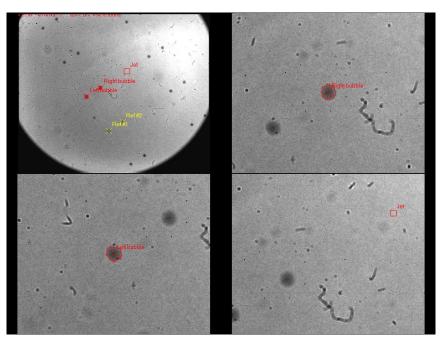
- HQ in Linköping, Sweden,
- Stockholm, Sweden
- London, UK,
- Los Angeles, USA

Image Systems is listed on the Swedish stock exchange (Nasdaq OMX)

3 companies having world leading products on niched markets









- Non contact, non-intrusive and high accuracy out-put data
- Founded 1985 in Linköping, Sweden and has ever since developed tools for image analysis

 Image Systems is the market leader in all segments for high-end post motion analysis solutions.



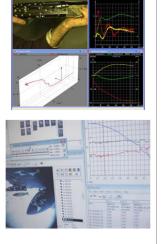


AUTOMOTIVE





DEFENCE



MANUFACTURING



BIOMECHANICS





AERONAUTICS





ONE TECHNIQUE - MILLIONS OF APPLICATIONS



INSTALLED BASE

- +1 500 software licenses installed an in operation
- ♦ +50 scanners in operation

- ♦ +Users in more than 40 countries
- Used globally by most military forces and weapons testing ranges

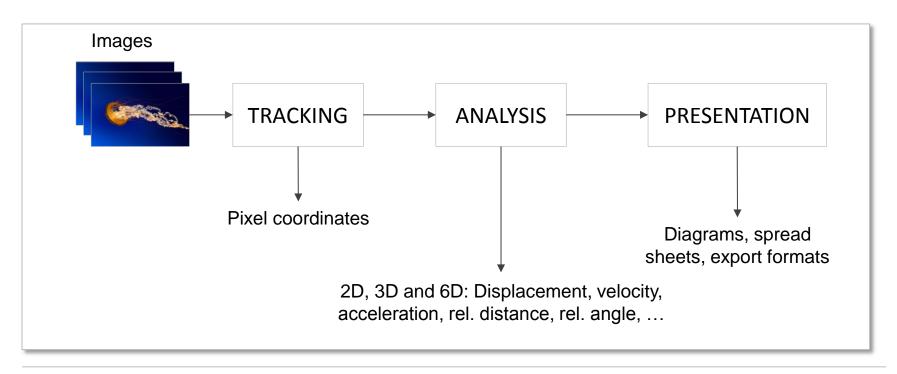




ANALYZING MOTION WITHIN IMAGES

THEORY BEHIND

- Using specific algorithms to locate any point in an image, we can track such points in a sequence of images at 0.1 pixels accuracy.
- Nowing the time lap between each image together with a referenced point in the image, we can calculate displacement, velocity, acceleration, rel. distance, rel. angle, etc of the point.





TRACKING & TRACKERS

CORRELATION

- Can track anything having a contrast, but is sensitive to rotation and change of luminance.
- The operator defines the correct position of what is to be tracked.





TRACKING & TRACKERS

QUADRANT SYMMETRY

- A tracker that knows how the marker should look.
- Locks mathematically to the centre of the marker.
- Not sensitive to rotation nor to luminance changes.
- Output is coordinate and angle.

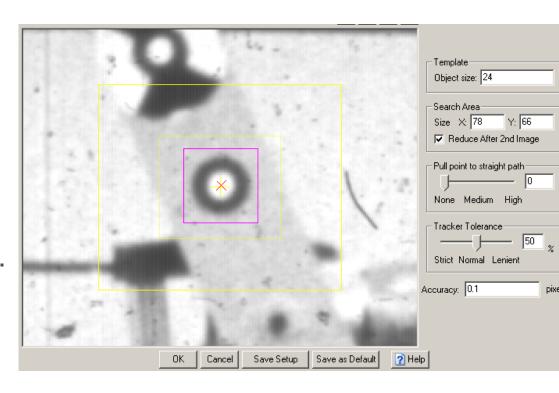




TRACKING & TRACKERS

CIRCULAR SYMMETRY

- A tracker that knows how the marker should look.
- Locks mathematically to the centre of the marker.
- Not sensitive to rotation nor to luminance changes.
- Output is coordinate.

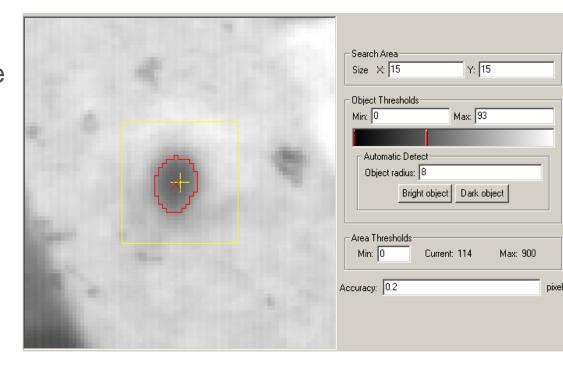




TRACKING & TRACKERS

CENTRE OF GRAVITY

- Using two static greyscale thresholds, this tracker identifies an area.
- Output is area centre coordinate.

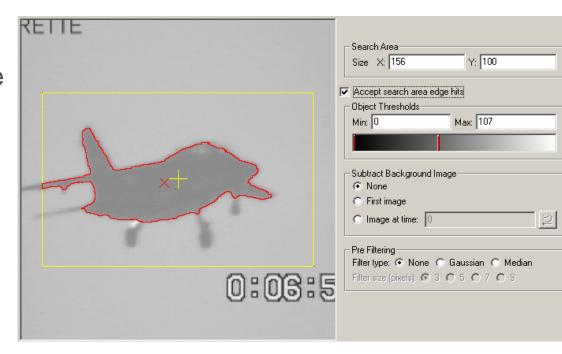




TRACKING & TRACKERS

OUTLINE

- Using two static greyscale thresholds, this tracker identifies an contour, all values between threshold values will inside the contour.
- Output is centre coordinate and contour.

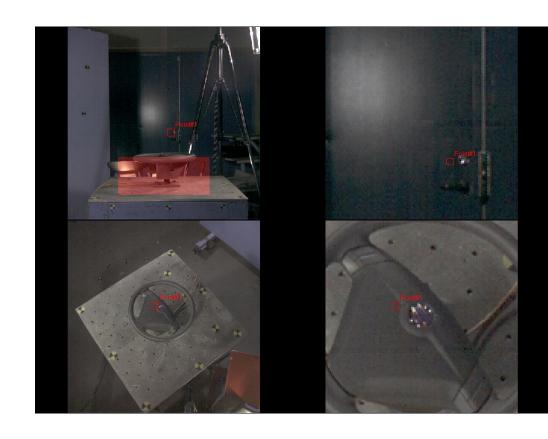




TRACKING & TRACKERS

ADVANCED OUTLINE

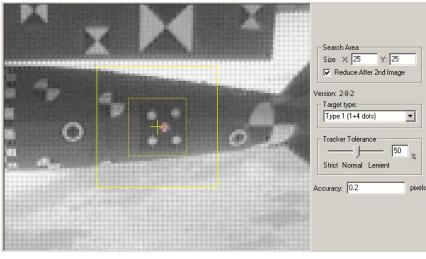
- This tracker is an advanced 'Outline' tracker which gives the operator special tools for operations on contours/outlines.
- Output is centre coordinate and contour.

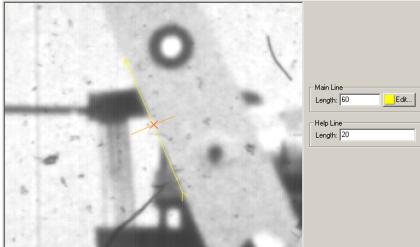




TRACKING & TRACKERS

MANUAL LINE
MXT TARGET
VIRTUAL
CONSTANT
INTERSECTION
CORNER CONTOUR







TRACKING AACCURACY

Algorithm	Uncertainty [px]
Correlation	0.5
QUAD	0.1
MXT	0.2
COG	0.2

▶ By using the difference in gray scale of different pixels, the software can manage to go below 1/10 of a pixel's accuracy

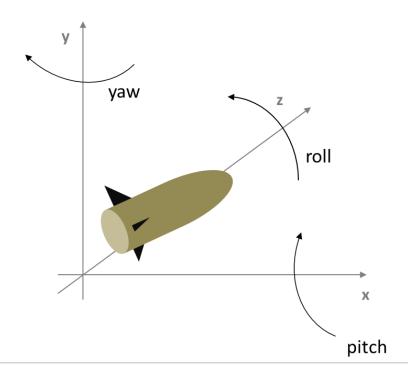


ANALYSIS

- Tracking means to follow a specific object/feature in an image sequence. We measure parameters such as
 - Displacements
 - Speed
 - Acceleration
 - Angles
- We can scale based on depth, chose to scale in pixels or meters and decide where we want to set the coordinate system

TRACKING 6 DIMENSIONS

- XYZ
- ROLL PITCH YAW



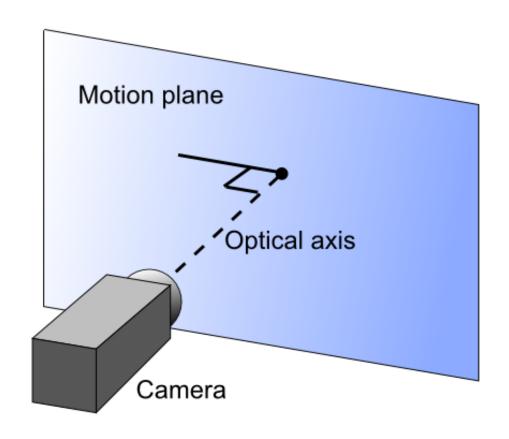


2D TRACKING

2D ANALYSIS

Concept:

- The camera is positioned at a 90° angle to the observed motion plane.
- Transform pixels to meters using a scale factor.
- The scale factor is constant for all objects in the motion plane.



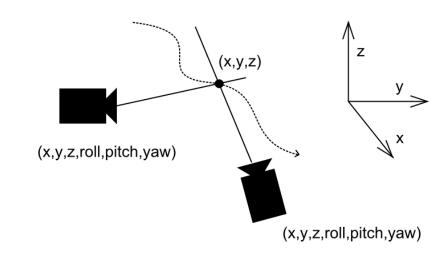


3D TRACKING

3D ANALYSIS

Triangulation/intersection

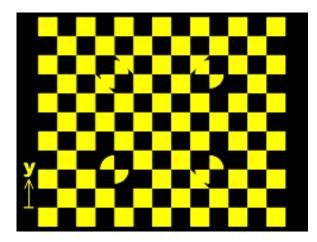
- Track an object from multiple camera views.
- A tracked 2D position in the image corresponds to a 3D line of sight.
- By intersecting multiple lines of sight, the 3D position is computed as the intersection point.
- The cameras must have an orientation (x, y, z, roll, pitch, yaw) in a common coordinate system, and the images must include timing information.





LENS CALIBRATION

- Calibrating camera & lens combination for:
 - Focal length
 - Principal point
 - Aspect ratio
 - Lens Distortion
- Two methods:
 - Calibration board
 - Wand calibration



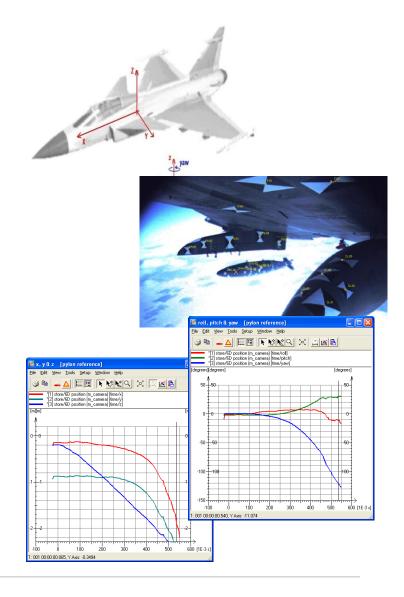




6D TRACKING

6D ANALYSIS

TrackEye can compute the 6D solution from one or multiple camera views. The rigid body must have multiple visible targets at any point in time. The motion of the rigid body can be described with six parameters: three position coordinates (x, y and z), which gives the position of a specific point on the body, and three attitude angles (roll, pitch and yaw), which gives its orientation in space.





ARENA TESTING

ARENA TESTING

- Traces of an explosion are detected using screens monitored by one or several cameras.
- Each screen has reference markers with a measured 3D position.
- Output is 3D position of objects together with certain object trace characteristics like speed, angle, area, etc.
- We also automatically can detect position, number and area of penetration holes in each plate.

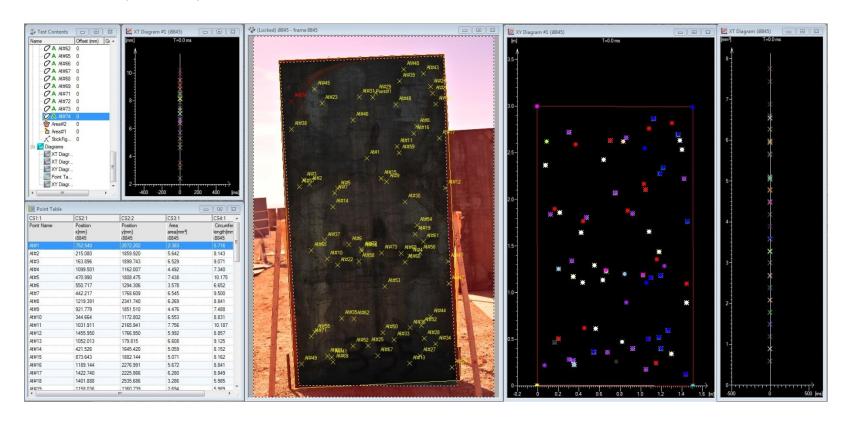






ARENA TESTING - AUTODETECT

- The results of each plate is calculated within minutes...
- Quantity x, y Location Area



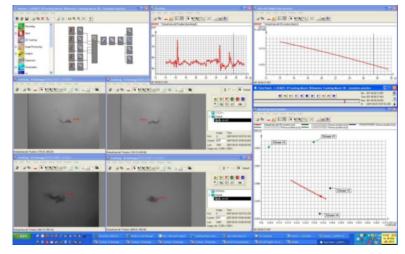


TRACKING MOUNTS

TRACKING MOUNTS

- Generates 3D position data using images & data from tracking mounts. Objects at large distances.
- Calibration & correction, integration with customer procedures.
- Coordinate transformations & refraction







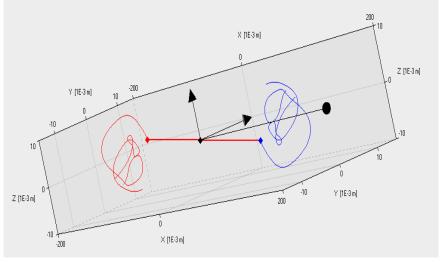
MIRROR TRACKER

MIRROR TRACKER

- Computing the 2D/3D coordinates & characteristica of a moving object from one/two trajectory trackers and optional fixed cameras.
- The 3D module computes the objects position (x, y, z) when the position of each fixed camera is known.

For the mirror tracker the camera positions are fixed but the image is transferred by a rotating mirror. This requires special calibration procedures



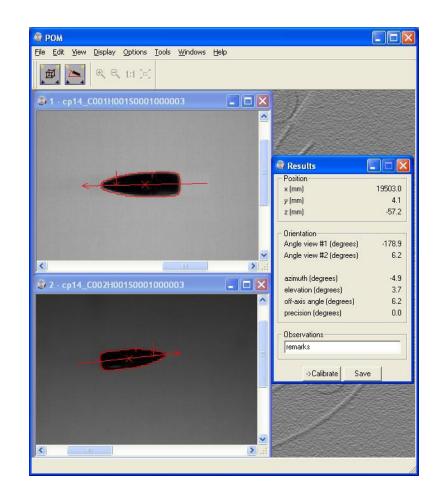




PROJECTILE ORIENTATION MEASUREMENTS

POM

- A dedicated stand-alone module to measure impact angles and 3D position of a bullet.
- Two cameras and two xray flashes create shadow images.
- Optimized for easy-of-use & short turn-around.
- A two-step procedure:
 - calibration
 - measurement

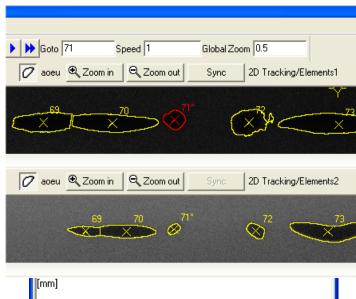


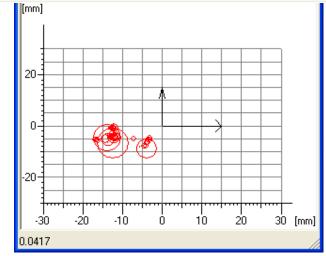


X-RAY MEASUREMENTS

X-RAY

- Analyzing 3D characteristics for plasma string droplets
- A series of X-ray flashes are used to create droplet shadows in 2D.
- Calibration to define geometry.
- Typical output data for droplets:
 - volume
 - velocity, rotation angle
 - estimated impact position







PRODUCTS

2 SOFTWARES – SAME CODE

TEMA & TRACKEYE

TRACKEYE

- Most powerful motion analysis software on the market
- Requires understanding of process of tracking by the user
- Modular features user creates his specific test
- Includes 6 DOF Stores release, Tracking Mounts, Mirror Tracker, ARENA features and SDK

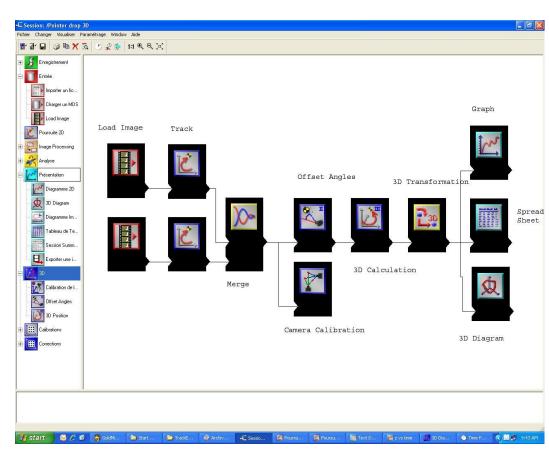
TEMA

- Dedicated for simplified use
- Uses the same tracking algorithms as TrackEye
- "Locked" features user creates pre-defined tests



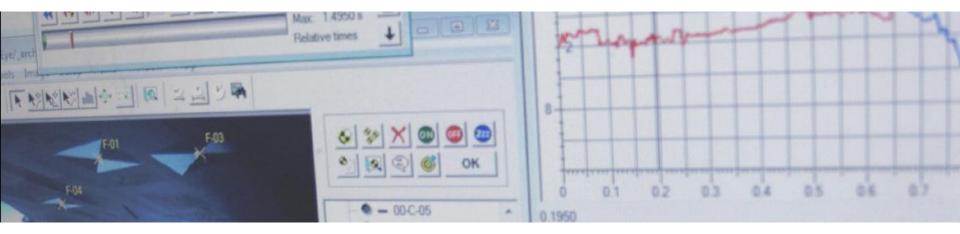
TRACKEYE

- Icon based build up of test implies complete flexibility
- Each icon can then be set up with the appropriate parameters
- The session can be saved as a template for repeated use with new image files
- Ability to insert your own functions and algorithms





TRACKEYE



REFERENCES

- · Aselsan, TK
- · Tübitak, TK
- · Rocketsan, TK
- TAI, Turkey
- · US Air Force, USA
- · US Army, USA
- US Marines, USA
- Korean Defense
- Italian Defense
- BAE Systems, UK
- Boeing, USA

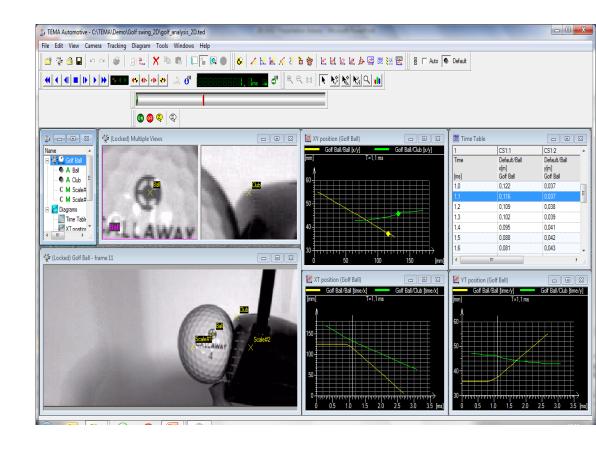
- · Lockheed Martin, USA
- MOD, UK
- BWB, Germany
- DGA, France
- Dassault, France
- Dutch Army Test Range
- · Embraer, Brazil
- · Israeli Air Force
- MIAT, Poland,
- · MHI, Japan
- · JDF, Japan

- INTA, Spain
- Air Force Test Range, Spain
- Brazil Air force
- · NASA, USA
- · Rafael, Israel
- Raytheon
- · Saab, Sweden
- Swedish MoD
- · and others...



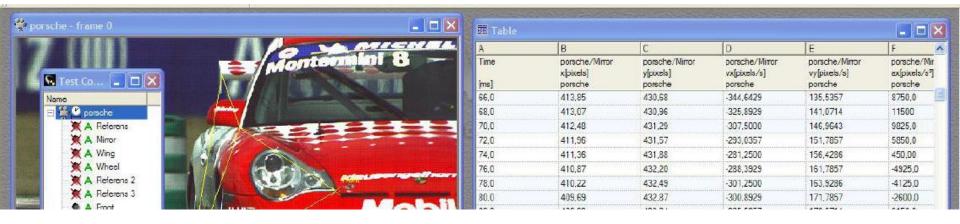


- Predefined functions
- Quick build-up of test scenarios





TEMA



REFERENCES

- OTEST, Turkey
- · Astrium, France
- Ajinomoto, Japan
- Bridgestone Sports, Japan
- · Canon, Japan
- · Nike Inc., USA
- Claas, Germany
- Coca Cola, Japan
- Daiwa Seiko, Japan
- NASA, USA
- · Drev, Canada
- U.S Army

- Federal Aviation Administration, USA
- Sharp, Japan
- Fuji Electric, Japan
- Fujitsu, Japan
- Hofstra University, USA
- Indian Head, USA
- HSVA, Germany
- Nikon, Japan
- Citroën, France
- · Volvo, Sweden
- DaimlerChrysler, USA

- Alstom, France
- KIA Motors, Korea
- AutoLiv, global
- Lear Seating, USA
- · Mitsubishi, Japan
- Nissan, Japan
- Peugeot, France
- Bridgestone, Japan
- Volkswagen, Germany
- CEAGA, Spain
- DaimlerChrysler, Germany
- and many more...



QUESTIONS?



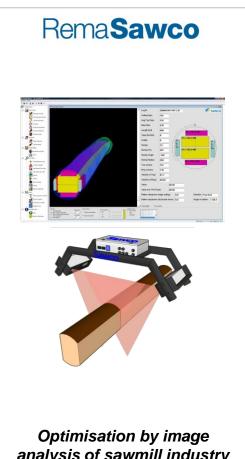
IMAGE SYSTEMS GROUP

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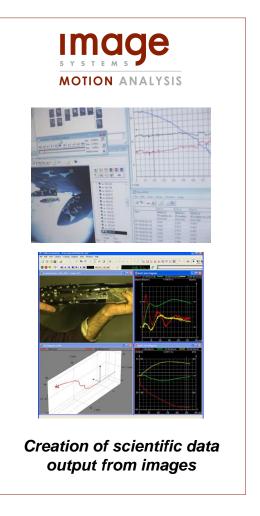




Optimisation of image quality and output in broadcast and movie industry



analysis of sawmill industry





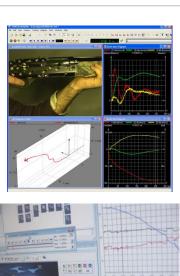
WIDE VARIETY OF APPLICATIONS AND SEGMENTS

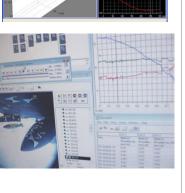
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